



# **Temperature Controllers**

# From simple control to advanced control



MSA SYSTEM - (11) 3961-1171 - comercial@msacontrol.com.br

# **Temperature Controller Selection Guide**

				Color LCD		Compact	Plug & socket connection
	M SYS	<b>A</b> STEM	2347	2349 - 23	2346 2346 2346		
Mode	el		PXF4	PXF5	PXF9	PXR3	PXR4
		96 × 96			✓		
Pane	l size	48 × 96		1			
in mm	48 × 48	✓				✓	
		48 × 24				✓	
		100–240 V AC	✓	✓	1	✓	✓
Power supp	r supply	24 V DC	✓	✓	✓	✓	✓
		RS-485 (Modbus)	✓	✓	✓	✓	
Comr	nunicatior	RS-485 (Z-ASCII)				✓	
	namoutor	Loader interface	✓	1	✓		
Displa	av		4-digit	4-digit	4-digit	4-digit	4-digit
			_	-	-	Euro-style terminal block,	8-pin or 11-pin, M3.5
lect	rical conne	ection	M3 screw te	rminal, for wire with	terminal lug	for bare wire or wire ferrule	screw terminal socket
Reading accuracy		±0.2% FS	±0.2% FS	±0.2% FS	±0.5% FS	±0.5% FS	
Samp	oling time		50 ms	50 ms	50 ms	500 ms	500 ms
	No. of PV	/ input	1	1	1	1	1
		RTD	✓	✓	✓	✓	✓
		тс	✓	✓	1	✓	✓
	Sensor	Voltage/current	✓	✓	✓	✓	✓
		Thermistor					
nput		Remote setpoint	✓	✓	✓		
		Current transformer	✓	✓	1		
	Options	Valve position		✓	✓		
		Digital	≤ 3	≤ 3	≤ 3	≤ 2	
		Relay contact	 ✓	 ✓			✓
		SSR/SSC	✓ (SSR only)	✓ (SSR only)	✓ (SSR only)		· ·
	Control	Linear current	✓ (CORCORD)	✓ (Controlling)	✓ (CORCORD)		 ✓
	output	Linear voltage	 ✓	·	· · · · · · · · · · · · · · · · · · ·	•	
tout			 ✓	 ✓	✓		
Output		Motor-operated valve	✓	✓ ✓	✓ ✓	✓	
		Transfer output (current)	<u>↓</u>	✓ ✓	↓ ↓	•	
	Options	Transfer output (voltage)	•	•	•		
		Power to transmitter	< 0	~ 5	F		< 0
		Digital output	≤ 3	≤ 5	≤ 5	≤ 2	≤ 2
		ON-OFF	<u> </u>	✓	1	4	1
Contr	ol	PID*	<u>√</u>	1	· ·	✓ ✓	<b>v</b>
‰wit	h auto-	Fuzzy*	<b>√</b>	·	1	<b>√</b>	<i>·</i>
unin		Self tuning		✓	✓	<b>√</b>	✓
anni	9	PID 2*	✓	✓ 	✓ ✓		
		2-degree-of-freedom PID*	✓	✓	<b>√</b>		
		Ramp soak	64 steps	64 steps	64 steps	8 steps	8 steps
		No. of PID pallettes	8	8	8		
Other	S	No. of SVs	8	8	8	4	
		Manual operation	✓	✓	✓		
		User key	1	1	1		CONTRO
Page			4-9	4-9	4-9	10-13	10-13

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Module Type Temperature Controllers

Simple	High-end	Thermostat
Simple	ingir-end	mermostat
Pile Marcal Pile	12200	
~3 <u>88</u> 9.	01 12 346	1234
9000	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
PXE4	PXH9	PXR3
PAE4	PAR9	PARJ
✓		
		✓
✓	✓	1
	✓	
		4
4-digit	5-digit	4-digit Euro-style terminal block,
M3 screw terminal, fo	or wire with terminal lug	for bare wire or wire ferrule
±0.5% FS	±0.1% FS	±0.5% FS
200 ms	50 ms	2 s
1	2	1
✓	✓	
~	<b>√</b>	✓
	✓	1
	✓	•
	•	
	✓	
	≤ 9	
✓	✓	✓
✓ (SSR only)	1	
	✓	
	✓	
	≤ 2	
< 2	✓ < 0	< 2
≤ 2 ✓	≤ 9 ✓	≤ 2
· · · · · · · · · · · · · · · · · · ·	· ·	
· ✓		
✓	✓	
	64 steps	
	7	
	7	
	✓	
44.45	3	00.00
14-15	16-19	22-23

Common Specifications				
Size	30 (W) × 100 (H) × 85 (D) mm			
Power supply	24 V DC			
Accuracy	±0.3% FS			
Sampling time	200 ms			
Communication	RS-485 (MODBUS)			
Loader communication	RS-232C (MODBUS)			
Installation	Rail mount or wall mount			
Control Module (PUMA/PUM	B) 2 or 4			
No. of inputs Sensor				
	TC, RTD, voltage/current			
No. of outputs				
Control output signal	Relay contact, current, SSR/SSC			
Auto, manual, remote	On/off, PID, heating/cooling			
Options	Auto, manual, remote CT input (4 or 8)			
Event I/O Module (PUME) No. of DIs	8			
No. of DOs	8			
Output type Analog I/O Module (PUMV/P	Relay contact or transistor			
No. of Als	4			
Input signal	TC, RTD, voltage/current			
No. of AOs	4			
Output signal	4–20 mA DC			
CC-Link Communication Module (PUMCL)				
Programless Communication	with Mitsubishi PLC (PUMCM)			
PROFIBUS Communication I	Module (PUMCP)			
Ethernet Communication Module (PUMCE)				
	· · · · ·			

# Micro-Controller X **PXF**



# Superior Versatility and Flexibility for a Wide Range of Applications



PXF9 96 × 96 × 58 mm



PXF5 48 × 96 × 58 mm



PXF4 48 × 48 × 58 mm



# Fast and Precise control

- Sampling time 50 ms
- Control 100 ms

# Universal Input

- Accept any signal
- User can change the input type later on

# Variety of Control Functions

• On-off

• Fuzzy

• PID

- PID2
- Two-degree-of-freedom PID
- Motor-operated-valve control
- Self-tuning
- Bus-Powered USB Interface

For configuration and data viewer software



# Compact Design

Shallow body with 58-mm depth

# Easy-to-See Display

- Bright and clear color-LCD
- Tallest character height in market
- PV indication in white

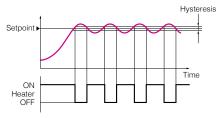






### **On-Off Control** Simple and Basic Control

When process value (PV) is below the set value (SV), PXF turns on the output to energize the heater, and vice versa. In this way, PXF keeps the temperature constant by turning the output on and off based on the SV as a threshold.

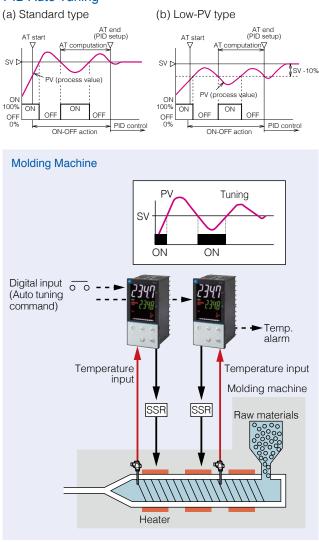


## **PID Control with Auto Tuning**

#### Typical Control Based on PID Theory

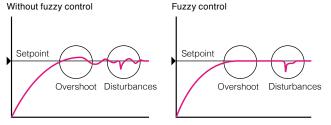
The controller calculates optimal PID parameters. There are 2 types of auto-tuning functions; the standard type (auto-tuning with reference to SV) and the low-SV type (auto-tuning with reference to the value 10% below SV). The low-SV type auto tuning is useful when you want to avoid overshoots. You can also set the PID parameters manually.

## **PID Auto Tuning**



# **Fuzzy Control with Auto Tuning**

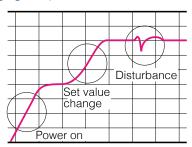
Suppresses Overshoot by Fuzzy Calculation



ONTRO

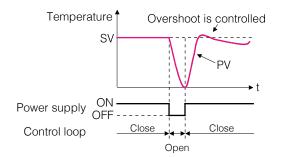
# Self Tuning Control

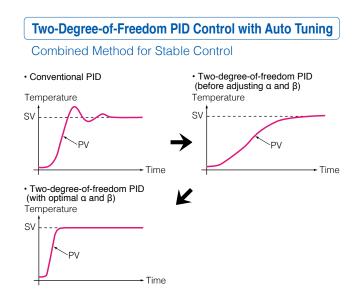
For Changing Temperature



# PID2 Control with Auto Tuning

Suppresses Overshoot and Undershoot



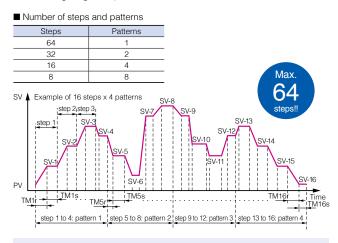




# Functions for better user experience

### Simple Program Control (Ramp Soak Function)

PXF automatically changes SV to the preset values at preset times. You can set up to 64 steps and 15 types of operation patterns. For example, when you bake four kinds of bread, you can divide 64 steps into four patterns to set suitable temperature for each bread. You can start/stop/suspend the operation using a user key, parameter setting, digital input, or communication.







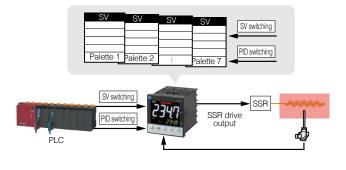
## Heating and Cooling Control (option)



SV and PID selection

#### Easy Switching Among 8 Presets

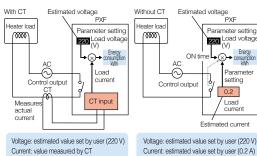
Enables optimum PID setting for changing process, materials, or PV. You can perform SV selection only, PID selection only, or PID selection according to PV.





## **Simple Watt-Hour Metering Function**

#### Tells You the Energy Consumption



## **Operating Days Alarm**

Indicator or alarm output alert you when the number of days operated has reached the limit you set.



For Well-Timed Maintenance

Energ

nsump kWh Paramete setting

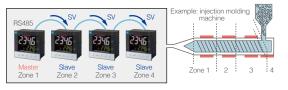
0.2

Load current

#### Soft Start Saves Energy at Startup

# **RS-485** Communication (option)

Multi-drop master function in combination with the twodegree-of-freedom PID control enables synchronous heating control.



- Parameter values can be copied to multiple PXFs simultaneously.
- Communication with PC, HMI, or PLC



## Heater Burnout Alarm (option)

#### Quickly Informs You a Failure

- A current transformer (CT) is required.
- The power supply voltage and the alarm action point must be configured beforehand.

## **Transfer Output (option)**

Temperature Signals to External Devices

Up to 5 Alarms (PXF4: up to 3) Alarm Output (option)

**Digital Input (option)** SV Can be Switched Externally

# **Remote SV Input (option)**

SV Can be Configured Externally

# MSA MSA SYSTEM CONTROL

# Specifications

General				
Power supply voltage	100 V (-15%) to 240 V (+10%) AC, 50/60 Hz, or 24 V (±10%) AC/DC			
	Model	100 to 240 V AC	24 V DC/AC	
Power consumption	PXF4	10 VA MAX.	5 VA MAX.	
	PXF5 & PXF9	13 VA MAX.	8 VA MAX.	
Insulation resistance	≥ 20 MΩ (at 500 V DC)			
Withstand voltage	Between the power source and other terminals: 1500 V AC for 1 min Between the relay output and other terminals: 1500 V AC for 1 min Others: 500 V AC for 1 min			
Input impedance	<ul> <li>Thermocouple, mV input: ≥ 1 MΩ</li> <li>Current input: ≤ 150 Ω (built-in diode)</li> <li>Voltage input: About 1 MΩ</li> </ul>			
Allowable input voltage	<ul> <li>DC voltage input: ≤ ±35 V</li> <li>Current input: ≤ ±25 mA</li> <li>Thermocouple, RTD, mV input: ≤ ±5 V</li> </ul>			
Effect of signal source resistance	<ul> <li>Thermocouple, mV input: ±0.3%FS ±1 digit per 100 Ω</li> <li>Voltage input: ±0.3%FS ±1 digit per 500 Ω</li> </ul>			
Allowable wire resistance	RTD: ≤10 Ω per wire			
Input value correction	<ul> <li>(a) User adjustment: ±50%FS for each of zero and span point</li> <li>(b) Process value shift: ±10%FS</li> <li>(c) Input filter: 0.0 to 120.0 s (filter is off when set to 0.0)</li> <li>(d) Square root extraction: -0.1 to 105% (OFF if set to -0.1%)</li> </ul>			
Noise reduction ratio	Normal mode: 40 dB (50/60 Hz) Common mode: 120 dB (50/60 Hz) Between input and power supply: ±1°C at 220 V AC, 50/60 Hz			
Temperature effect on sensitivity	±0.3%FS per 10°C			

## Display and keys

Туре	Backlit LCD
Keys	5 embossed keys
Cotents	PV: 11-segment, 4-digit [white] SV: 11-segment, 4-digit [green] Parameter name: 7-segment, 4-digit [orange] Status indicator: 5 42
Luminance setting	4 levels
User key	Allows you to switch between: auto/manual, standby on/off, remote SV, ramp/soak, etc.

Structure

Structure	
Installation	Panel mounting
Electrical connection	M3 screw terminal
Case	<ul> <li>Material: ABS, PPO</li> <li>Non-combustibility grade: UL94V-0 equivalent</li> <li>Color: black</li> </ul>
IP rating	<ul> <li>Panel front side: IP66, NEMA-4X equivalent (When the panel is mounted using our genuine packing. Not water-proof if mounted closely together.)</li> <li>Body: IP20 equivalent (slits on top and bottom)</li> <li>Terminals: IP00 equivalent</li> </ul>
Weight	PXF4: approx. 100 g, PXF5: approx. 170 g, PXF9: approx. 220 g

**PV** input

PV input	
No. of inputs	1
Signal	Thermocouples, RTD, voltage, or current *See a separate table for measurement range.
Input setting	Programmable scale
Sampling rate	50 ms
Indication accuracy (at 23°C)	<ul> <li>Thermocouple input: either ±1°C ±1 digit or ±0.3% of indicated value ±1 digit, whichever is larger * except:</li> <li>Thermocouple B: 0 to 400°C: no accuracy assurance</li> <li>Thermocouple B: 0 to 500°C: ±3°C ±1 digit</li> <li>Thermocouples of which measuring range is between -200°C and -100°C: ±2°C ±1 digit</li> <li>RTD input: ±0.8°C ±1 digit to ±0.2% of indication value ±1 digit, whichever is larger</li> <li>mV input, voltage input, current input: ±0.3%FS ±1 digit</li> </ul>
Overrange · underrange	Out of the range between -5% and 105% FS (accuracy is not assured between -5 and 0, and between 100 and 105%FS) *Pt (-200°C to 850°C) input, 0-10 V DC input, thermocouple E: Out of the range between -5 to 102% of FS

Remote SV input (option)			
No. of inputs	1		
Signal	Voltage: 0–5 V DC, 1–5 V DC, 0–10 V DC Current (250 $\Omega$ resistor is required): 0–20 mA DC, 4–20 mA DC		
Impedance	Approx. 1 MΩ		
Sampling rate	50 ms		

	SIEMI CONIKOL
Current transforme	er input (option)
Input type	Single phase CT, 1 point For 1 A to 30 A: CTL-6-S-H
Input type	For 20 A to 100 A: CTL-12-S36-8
Detection range	1 A to 100A
Accuracy	Setpoint ±5%FS
Resolution	0.1A
ON time necessary for detection	≥ 300 ms
Digital input (optio	n)
No. of inputs	PXF5 and PXF9: up to 3 PXF4 standard version: 1 PXF4 motorized valve control version: 3
Switch	Volt-free contact or transistor
Contact capacity	5 V DC, about 2 mA (per point)
Input judgment	ON voltage: 2 V DC or lower OFF voltage: 3 V DC or higher
Input pulse width	≥ 50 ms
Functions	Remote mode selection, SV changeover, control standby, AT startup, timer startup, alarm unlatch, program selection, start/stop/ reset, PID switching (normal/reverse), etc.
Valve position feed	back signal input (option for PXF5 and PXF9 only)
Resistance range	100 $\Omega$ to 2.5k $\Omega$ , three-wire
Resolution	0.5% FS
Accuracy	±1.0%FS
Temperature effect on sensitivity	±0.5%FS per 10°C
Burnout function	None
Alarm output (option	on)
No. of points	Relay contact Shared COM: PXF4: ≤3, PXF5 & PXF9: ≤5 Independent COM: PXF4: ≤2, PXF5 & PXF9: ≤3
Contact	<ul> <li>Contact structure: SPST-NO</li> <li>Contact capacity: 250 V AC / 30 V DC, 1A (resistive load)</li> <li>Minimum ON/OFF current: 10 mA (5 V DC)</li> <li>Mechanical life: 2 20 million operations (100 operations/min)</li> <li>Electrical life: 2 100,000 operations (rated load)</li> </ul>
Functions	Alarm output, main unit control mode output, program status out put, control output 1 and 2, etc.
Output cycle	100 ms
Alarm	· · · · · · · · · · · · · · · · · · ·
No. of alarms	PXF4: ≤ 3
Alarm type	PXF5 & PXF9: ≤ 5 (depends on the number of DO) Process value (upper limit/lower limit, absolute/deviation, range) device error, etc.(non-excitation, delay, latch, timer function available)
Heater current alarm function (option)	available)         Current transformer (CT) is to be prepared separately         Detectable range: 1 A to 100 A         Detected current resolution: 0.1A         Setting resolution: 0.1A         Hysteresis: 0.0 to 100.0 A
Transfer output (or	
No. of points	1
Туре	0-20 mA DC / 4-20 mA DC / 0-5 V DC / 1-5 V DC / 0-10 V DC / 2-10 V DC • Guaranteed output range: 0-21 mA DC / 0-10.5 V DC • Accuracy: ±0.2%FS (±5%FS at 1 mA or smaller) • Resolution: ≥ 10,000 • Load resistance: ≤ 500 Ω (current), ≥ 10 kΩ (voltage)
Output cycle	100 ms
Contents	PV, SV, DV, MV
Additional function	Scaling function
	<b>3</b>



# **Specifications**



Baud rate: 9600 bps, 19200 bps, 38.4 kbps, 115.2 kbps

The function in which slave devices can be operated by a master device by connecting several temperature controllers. • Programless communication The function in which a temperature controller can be connected the several several

64 steps × 1 pattern, 32 steps × 2 patterns, 16 steps × 4 patterns,

Control option: control by digital input or status output by digital

• By connecting a current transformer (to be prepared separately), electric power consumption of the heater can be displayed.

(Electric power is calculated based on the fixed voltage value

 Indicates the number of days the controller has been operated and activates alarm output (optional) when it exceeds the

Useful for preventive maintenance because it let you know the

Current transformer (CT) is to be prepared separately.

Current detection range: 1 A to 100 A

appropriate time for maintenance work.

Modbus RTU, half-duplex bit serial, asynchronous communication

≤ 32 units

output

Guaranteed soak Repeat action PV start Delay start Power failure recovery Memory backup on EEPROM

on non-volatile memory

by watchdog timer

, you set.)

setpoint.

-10°C to 50°C

-20°C to 60°C

≥ 30 min

≤ 90% RH (no condensation)

during transportation: ≤ 9.8 m/s<sup>2</sup> (1 G)

during transportation: ≤ 294 m/s² (30 G)

**Operation and storage conditions** 

three-level password

Data bits: 8 bits. Parity: odd, even, none

to a PLC without program. Supported PLCs: Mitsubishi PLC Q series Siemens PLC S7 series

or 8 steps × 8 patterns (1 step = 2 segments)

Time setting: "Hour, Minutes" or "Minutes, Seconds"

≤ 500 m (total connection length)

Multidrop master function

**RS-485 communication** 

Serial characteristics

Connection

distance

Communication

Additional function

Other functions

Data backup at power

Ramp soak

outage

Self-diagnosis

Simple watt-hour

. metering function

Operating days alarm

Password

Operating

Humidity

Vibration

Impact

temperature Storage temperature

Warm-up time

#### **Control output**

≤ 2		
Relay contact output (SPST-NO) Proportional cycle: 1 to 150 s Contact capacity: 250 VAC / 30 VDC, 3A (resistive load) Minimum ON/OFF current: 10 mA (5 V DC) Mechanical life: $\geq$ 20 million operations (100 operations/min) Electrical life: $\geq$ 100,000 operations (rated load) Relay contact output (SPDT) Proportional cycle: 1 to 150 s Contact capacity: 250 VAC / 30 VDC, 5A (resistive load) Mechanical life: $\geq$ 50 million operations (100 operations/min) Electrical life: $\geq$ 50 million operations (rated load) SSR drive output Proportional cycle: 1 to 150 s ON voltage: 12 V DC (between 10.7 and 13.2 V DC) OFF voltage: $\leq$ 0.5 V DC Maximum current: 20 mA DC Load resistance: $\geq$ 600 $\Omega$ Current output (0–20 mA DC / 4–20 mA DC) Accuracy: ±5%FS Load resistance: $\leq$ 500 $\Omega$ Voltage output (0–5V DC / 1–5 V DC / 0–10 V DC / 2–10 V DC)		
Current output (0–20 mA DC / 4–20 mA DC) Accuracy: $\pm$ 5%FS Load resistance: $\leq$ 500 $\Omega$		
Notified and the second secon		

Control

Control type		
On-off		
PID		
Fuzzy PID	Can be used in heating and cooling dual control. PID parameters are auto tuned.	
PID2		
Self tuning		
Two-degree-of-freedom PID	PID parameters are auto tuned.	
Position proportional PID (servo)	PXF4: without position feedback PXF5 and PXF9: with position feedback Full stroke time: ≥ 30 s	
Control mode	Auto/Manual/Remote * In manual mode, on/off control is performed with 100% MV or 0% MV. Mode changeover: • Auto ↔ Manual: Balanceless · bumpless • Auto/Manual→Remote: Balance · bumpless • Auto/Manual←Remote: Balance · bumpless	
Parameters		
Proportional band (P)	0.1% to 999.9%	
Integration time (I)	0 to 3200 s (invalidated when I = 0)	
Differential time (D)	0.0 to 999.9 s (invalidated when D = 0)	
Control cycle	100 to 900 ms (in 100 ms), 1 to 99 s (in seconds)	
Anti-reset windup	0 to 100% of measurement range	
Hysteresis band	50% of measurement range (for on/off action only)	
Number of SV and PID patterns	8: Changed by any of parameter setting, digital input, communication, user function keying, zone change.	

Maga	LIFO D	aont	range	
weas	uren	ient	ranu	

Input signal		Code (PvT)	Range [°C]	Resolution [°C]	
		PT1	0.0 to 150.0	0.1	
		PT2	0.0 to 300.0	0.1	
	Pt 100	PT3	0.0 to 500.0	0.1	
RTD		PT4	0.0 to 600.0	0.1	
NID		PT5	-50.0 to 100.0	0.1	
		PT6	-100.0 to 200.0	0.1	
		PT7	-199.9 to 600.0	0.1	
		PT8	-200 to 850	1	
	0 to 5 V DC	0-5V			
	1 to 5 V DC	1-5V			
DC voltage	0 to 10V DC	0-10	-1999 to 9999 (Range		
	2 to 10V DC	2-10	where scaling is al-	-	
	0 to 100mV DC	MV	lowed)		
DC current	0 to 20 mA DC	0-20			
DC current	4 to 20 mA DC	4-20			

Input signal		Code (PvT)	Range [°C]	Resolution [°C]
		J1	0.0 to 400.0	0.1
	J	J2	-20.0 to 400.0	0.1
	J	J3	0.0 to 800.0	0.1
		J4	-100 to 1000	1
		K1	0 to 400	0.1
	к	K2	-20.0 to 500.0	0.1
	ĸ	K3	0.0 to 800.0	0.1
		K4	-200 to 1300	1
	R	R	0 to 1700	1
	В	В	0 to 1800	1
Thermocouple	S	S	0 to 1700	1
mermocoupie	т	T1	-199.9 to 200.0	0.1
	I	T2	-199.9 to 400.0	0.1
		E1	0.0 to 800.0	0.1
	E	E2	-150.0 to 800.0	0.1
		E3	-200 to 800	1
	L	L	-100 to 850	1
	U	U1	-199.9 to 400.0	0.1
	5	U2	-200 to 400	1
	N	N	-200 to 1300	1
	W	W	0 to 2300	1
	PL-II	PL-2	0 to 1300	1

# **Ordering Code**

#### **PXF4 Standard Type**

Digit	Specification	Code
1-4	<pre></pre>	
1-4	48 × 48mm	PXF4
5	-	A
6	Control output 1>         Relay contact (SPST) *1         Relay contact (SPDT) *1         SSR drive output         Current output         Voltage output	A B C E P
7	(Control output 2)       None       Relay contact (SPST)       SSR drive output       Current output       Voltage output       Transfer output (current)       Transfer output (voltage)	Y A C P R S
8	(Revision code)	2
9	〈Alarm output〉 None 1 point 2 points 3 points 2 points (independent common)	0 1 F M J
10	(Power supply voltage / instruction manual) 100 to 240 V AC, Japanese & English 100 to 240 V AC, English 100 to 240 V AC, Chinese & English 24 V AC/DC, Japanese & English 24 V AC/DC, English 24 V AC/DC, Chinese & English	Y V W A B D
11	⟨Option⟩ None RS-485 communication Digital input (DI1) RS-485 communication + Digital input (DI1) RS-485 communication + Remote SV input * <sup>2</sup> RS-485 communication + CT input * <sup>3</sup>	1 M S V K J
12 13	-	00
10		l

\*2: When using current for the remote SV input, add a 250-ohm resistor to the input terminal. \*3: When using the CT input for heater burnout alarm, add one alarm output for it in the 9th code

#### PXF5 & PXF9 Standard Type

code.

Digit	Specification	Code
	<pre>〈Front dimensions W x H〉</pre>	
1-4	48 × 96 mm	PXF5
	96 × 96 mm	PXF9
5	-	A
	(Control output 1)	
	Relay contact (SPST)	A
6	Relay contact (SPDT)	В
0	SSR drive output	С
	Current output	E
	Voltage output	Р
	(Control output 2)	
	None	Y
	Relay contact (SPST)	A
7	SSR drive output	С
'	Current output	E
	Voltage output	Р
	Transfer output (current)	R
	Transfer output (voltage)	S
8	(Revision code)	2
	〈Alarm output〉	
	None	0
9	1 point	1
9	2 points	F
	3 points	M
	2 points (independent common)	J
	$\langle$ Power supply voltage / instruction manual $ angle$	
	100 to 240 V AC, Japanese & English	Y
	100 to 240 V AC, English	V
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	A
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	(Option)	
	None	1
	RS-485 communication	М
11	Digital input (DI 1 and DI2)	Т
	Remote SV input + Digital input (DI3) *1	н
	CT input + Digital input (DI1) *2	G
	RS-485 communication + Digital input (DI1)	V
	RS-485 + Digital input (DI3, DI4, DI5) + Auxiliary alarm output (AL4, AL5)	C
12	_	00
13		20
*1: Whe	n using current for the remote SV input, add a 250-ohm resistor to the inp	ut terminal.

<sup>1</sup>: When using current for the remote SV input, add a 250-ohm resistor to the input terminal. \*2: When using the CT input for heater burnout alarm, add one alarm output for it in the 9th

#### PXF4 Motorized Valve Control Type

Digit	Specification	Code
1-4	<pre> {Front dimensions W x H} </pre>	
1-4	48 × 48mm	PXF4
5	-	A
6	(Control output 1)	
0	Motorized valve control output (without PFB input)	Т
7	(Control output 2)	
	None	Y
8	(Revision code)	2
	〈Alarm output〉	
	None	0
9	1 point	1
	2 points	F
	2 points (independent common)	J
	Power supply voltage / instruction manual>	
	100 to 240 V AC, Japanese & English	Y
	100 to 240 V AC, English	V
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	A
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	(Option)	
11	None	1
	Digital input (DI 1, 2, 3)	D
	RS-485 communication + Digital input (DI1)	V
12		00
13	-	50

#### Separate order items

Current transformer	1 A to 30A	ZOZ*CCTL-6-S-H
	20 to 100A	ZOZ*CCTL-12-S36-8
Terminal cover		ZZPPXR1-A230
Parameter loader interface cable		ZZP*TQ501923C3
Shunt resistor (250 Ω±0.1%)		ZZPPXR1-A190
Panel mounting adapter for replacement from PXR7 to PXF4		ZZP*TQ502732C1



#### PXF5 & PXF9 Motorized Valve Control Type

Digit	Specification	Code
	<pre>⟨Front dimensions W x H⟩</pre>	
1-4	48 × 96 mm	PXF5
	96 × 96 mm	PXF9
5	-	A
	(Control output 1)	
6	Motorized valve control output (without PFB input)	S
	Motorized valve control output (with PFB input)	V
7	(Control output 2)	
'	None	Y
8	(Revision code)	2
	〈Alarm output〉	
	None	0
9	1 point	1
9	2 points	F
	3 points	M
	2 points (independent common)	J
	$\langle$ Power supply voltage / instruction manual $ angle$	
	100 to 240 V AC, Japanese & English	Y
	100 to 240 V AC, English	V
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	A
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	(Option)	
11	None	1
	RS-485 communication + Digital input (DI1, DI2, DI3)	U
12	_	00
13		50

#### Separate order items

Current transformer	1 A to 30A	ZOZ*CCTL-6-S-H
	20 to 100A	ZOZ*CCTL-12-S36-8
Terminal cover *1		ZZPPXF1-B100
Parameter loader interface cable		ZZP*TQ501923C3
Shunt resistor (250 Ω±0.1%)		ZZPPXR1-A190
*1: For PXF9, two covers are necessary for one unit.		

#### Scope of delivery

Controller, panel mounting adapter, water-proof packing, instruction manual

# **Micro-Controller X** PXR





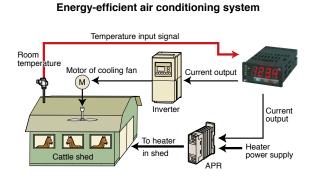


PXR3 48 × 24 × 98 mm

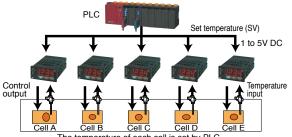
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# Compact Type and Plug & Socket Connection type

- Heating and cooling control
- Front waterproof structure
- Sampling time 500ms
- 2 DIs + 2 DOs available
- Options: alarm, RS-485 communication, transfer output, ramp soak



#### Optimal control of multiple heating devices

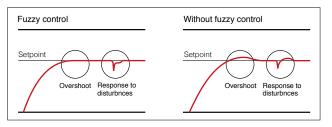


# YSTEM CONTROL

# Control Functions

## **Auto-Tuned Fuzzy Control**

PXR monitors the process temperature and suppress overshoot and effect of external disturbances based on the fuzzy logic, without increasing the startup time.

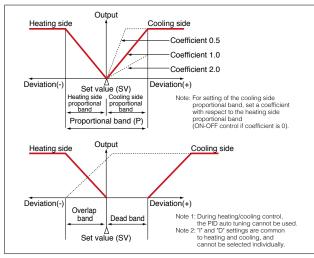


# **On–Off Control**

The temperature controller keeps the temperature stable by turning on the power supply for a heater when the process value is lower than the setpoint, and turning it off when the process value is higher than the setpoint. The controller works in on-off control if you set the parameter P to zero.

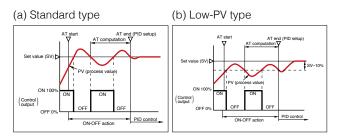
# Heating / Cooling Control (option for PXR3)

By using two control outputs, you can control both heating process and cooling process with a single controller.



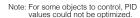
# **Auto-Tuned PID Control**

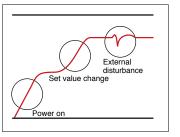
The controller calculates optimal PID parameters. There are 2 types of auto-tuning functions; the standard type (auto-tuning with reference to SV) and the low-SV type (auto-tuning with reference to the value 10% below SV). The low-SV type auto tuning is useful when you want to avoid overshoots. You can also set the PID parameters manually.



# **Self-Tuned PID Control**

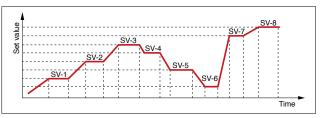
The controller tunes PID parameters when necessary; for example, at startup of the equipment, when the setpoint is changed, and/or the process temperature changed due to disturbance





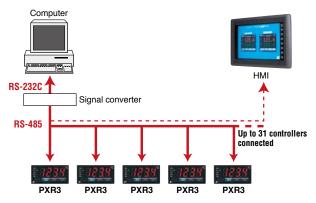
## Ramp Soak Control (option)

PXR automatically changes the setpoint to the preset values at preset times. You can set up to 64 steps and 15 patterns.



# **RS-485** Communication (option for PXR3)

Allows the temperature controller to communicate with a PC, PLC, or HMI.



# Transfer Output (option for PXR3)

PXR3 can send SV, PV, MV, or deviation of PV and SV, as 4-20 mA signal to an external device such as a recorder. Allows you to save the cost for a temperature sensor for recorder.



# PXR3 and PXR4 MSA MSA Specifications

#### General

General	
Power supply voltage	100 V (-15%) to 240 V (+10%) AC, 50/60 Hz, or 24 V (±10%) AC/DC
Power consumption	100 V AC: ≤ 6 VA (PXR3), ≤ 8 VA (PXR4) 220 V AC: ≤ 8 VA (PXR3), ≤ 10 VA (PXR4) 24 V AC/DC: ≤ 8 VA (PXR3), ≤ 10 VA (PXR4)
Insulation resist- ance	≥ 20 MΩ (at 500 V DC)
Withstand voltage	Between the power source and the ground terminal: 1500 V AC for 1 min Between the power source and others: 1500 V AC for 1 min Between the ground and relay outputs: 1500 V AC for 1 min Between the ground and alarm outputs: 1500 V AC for 1 min Others: 500 V AC for 1 min
Input impedance	Thermocouple, mV input: ≥ 1 MΩ Current: 250 Ω (external resistor) Voltage: ≥ 450 kΩ
Allowable signal source resistance	Thermocouple: $\leq 100 \Omega$ Voltage: $\leq 1 k\Omega$
Allowable wire resistance	RTD: $\leq$ 10 $\Omega$ per wire
Input value correction	Process value shift: $\pm 10\%$ FS Input filter: 0 to 900.0 s settable in 0.5 s steps (first order lag filter)
Noise reduction ratio	Normal mode noise (50/60 Hz): $\geq$ 50 dB Common mode noise (50/60 Hz): $\geq$ 140 dB
Display and keys	
Туре	LED, 3 keys
Cotents	SV and PV: 4 digits, 7-segment (PXR3: SV/PV switching, PXR4: SV/PV independent display) Status indicator: control output, alarm
Structure	
Installation	Panel flush mounting Can be mounted to rail/wall by using the DIN rail mounting adapter available as option.
Electrical connection	PXR3: euro-style terminal PXR4: 8-pin or 11-pin, M3.5 screw terminal socket
Case	Plastic (non-combustible grade UL94V-0 equivalent), black
IP rating	Front waterproof structure: NEMA4X (IP66 equivalent) *When mounted on panel with our genuine packing. Waterproof feature unavailable in close mounting of multiple units. Rear case: IP20

No. of inputs	1
Signal	Thermocouples, RTD, voltage, or current *See a separate table for measurement range.
Sampling rate	0.5 s
Indication accuracy(at 23°C)	Thermocouple: ±(0.5% of measuring range) ±1 digit ±1°C For thermocouple R at 0 to 500°C: ±(1% of measuring range) ±1 digit ±1°C For thermocouple B at 0 to 400°C: ±(5% of measuring range) ±1 digit ±1°C RTD, voltage/current: ±(0.5% of measuring range) ±1 digit
Burnout	In the thermocouple input version or the RTD input version, a user can select either the upper or the lower limit to which the control output should go when a sensor burnout occurs.
Digital input (op	tion for PXR3)
No. of inputs	≤2
Switch	Volt-free contact or transistor
Contact capacity	5 V DC, about 2 mA (per point)
Input judgment	ON voltage: ≤ 2 V DC OFF voltage: ≥ 3 V DC
Input pulse width	≥ 0.5 s
Functions	Set value (front SV, SV1 to 3) changeover Control action start / stop Ramp/soak action start / reset Auto tuning start / stop Alarm latch cancel Alarm latch cancel Alarm on- or off-delay timer: setting range 0–9999 s in 1 s steps
Alarm output	
No. of alarms	≤2
Alarm type	Absolute alarm, deviation alarm, zone alarm with upper and lower limits for each Hold function available Alarm latch, Excitation/non-excitation selecting function provided
Alarm ON-delay	Delay setting 0 to 9999 s settable in 1 s steps
Contact	Relay contact (SPST-NO): 220 VAC / 30 VDC, 1 A (resistive load) Mechanical life: 10 million operations (no load) Electrical life: 100,000 operations (rated load) Minimum switching current: 10 mA (5 V DC). Output cycle: 0.5 s

#### **Control output**

	Control output 1	Control output 2 (option for PXR3, for cooling/heating control)	
Type       220 VAC / 30 VDC, 34 (restrive load)       Mechanical life: 10 million operations (no load)         Electrical life: 10 million operations (rated load)       Minimum switching current: 10 mA (5 VDC), PXR4: 100 mA (24 VDC)       Minimum switching current: 10 mA (5 VDC)         • SSR / SSC drive (voltage pulse):       • SSR / SSC drive (voltage pulse):       • SSR / SSC drive (voltage pulse):         • OF: ≤ 0.5V DC       • OF: ≤ 0.5V DC       • OF: ≤ 0.5V DC         • Maximum current: 20 mA       • Maximum current: 20 mA		<ul> <li>Relay contact: SPST-NO, 220 VAC / 30VDC, 3A (resistive load) Mechanical life: 10 million operations (no load) Electrical life: 100,000 operations (rated load) Minimum switching current: 10 mA (5 V DC)</li> <li>SSR/SSC drive (voltage pulse): ON: 12–16 V DC</li> <li>OFF: ≤ 0.5V DC</li> </ul>	
Control type	PID control (with auto tuning, self-tuning) Fuzzy control (with auto tuning)	PID control (with auto tuning)	
Parameters	On/off action if $P = 0$ . Proportional action when I, $D = 0$ .	P,I,D=0: ON/OFF action (without dead band) for heating and cooling I,D=0: Proportional action	
Proportional band (P)	0 to 999.9% of measuring range settable in 0.1% steps	Heating side: 0 to 999.9 % of measuring range Cooling side: Heating side "P" × cooling side coefficient Cooling side proportional band coefficient: 0 to 100.0 On/off action if P=0	
Integration time (I)	0 to 3200 s settable in 1 s steps	0 to 3200 s	
Differential time (D)	prential time (D) 0 to 999.9 s settable in 0.1 s steps 0 to 999.9 s		
Proportional cycle	1 to 150 s settable in 1 s steps Only for relay contact output or SSR/SSC drive output	1 to 150 s Only for relay contact output or SSR/SSC drive output only	
Control cycle	0.5 s	0.5 s	
Anti-reset windup	up         0 to 100% of measuring range         0 to 100% of measuring range           Automatically validated at auto tuning         0 to 100% of measuring range		
Hysteresis band	and 0 to 50% of measuring range 50% of measuring range common to heating and cooling sides, For on/off action only		
Overlap dead band	_	±50% of heating side proportional band	



#### Transfer output (option for PXR3)

No. of points	1
Туре	4–20 mA DC • Load resistance: ≤ 500 Ω • Accuracy: ±0.3%FS at 23°C • Resolution: ≥ 2000
Output cycle	500 ms
Contents	PV, SV, DV, MV

#### RS-485 communication (option for PXR3)

Data bits: 8 bits. Parity: odd, even, none
Baud rate: 9600 bps
≤ 32 units, multi drop
≤ 500 m (total connection length)
lsolated type Manufacturer: OMRON Co., Ltd. (Japan) Model: K3SC-10
≤ ≤ I:

#### **Other functions**

Ramp soak (option)	2 program pattern of 4 steps each, or 1 program parttern $\times$ 8 steps On PXR3, a user can use the digital input to start/reset the ramp soak action.
Data backup at power outage	on non-volatile memory
Self-diagnosis	by watchdog timer

#### Operation and storage conditions

Operating tempera- ture	-10°C to 50°C
Storage tempera- ture	-20°C to 60°C
Humidity	≤ 90% RH (no condensation)

#### **Measurement range**

Input signal		Range(°C)	Range(°F)
RTD	Pt100	-150 to 850 *	-238 to 1562
	J	0 to 800	32 to 1472
	К	0 to 1200	32 to 2192
	R	0 to 1600	32 to 2912
	В	0 to 1800	32 to 3272
Thermocouple	S	0 to 1600	32 to 2912
	Т	-150 to 400	-238 to 752
	E	-150 to 800	-238 to 1472
	N	0 to 1300	32 to 2372
	PLI	0 to 1300	32 to 2372
DC voltage	1 to 5V	cooling range	-1999 to 9999
DC current	4 to 20mA	scaling range -1999 to 999	

For 4–20 mA current input, add the provided 250-ohm resistor to the input terminal.
 For temperatures of 1000°C (1832°F) or above, the decimal point does not appear on the display.

By editing the parameter, you can switch the input type setting among RTD and thermo-couples, or between voltage and current.

# Ordering Code

	0		
	4 5 6 7 8 9 10 11 12	13 14	
	PXR 3 2 -	- F	
Digit	Specification	Code	
4	<front dimensions="" h="" w="" ×=""></front>		
4	48 × 24 mm	3	
	<input signal=""/>		
	Thermocouple °C	T	
-	Thermocouple °F	R	
5	RTD Pt100 Ω 3-wire °C	N	
	RTD Pt100 Ω 3-wire °F	S	
	1 to 5 V DC 4 to 20 mA DC	A B	
	<control 1="" output=""></control>		
	Relay contact output	A	
6	SSR/SSC driving output	c	
	4 to 20 mA DC output	Ē	
	<control 2="" output=""></control>		
	None	Y	
7	Relay contact output*1	A	
	SSR/SSC driving output*1	C E	
	4 to 20 mA DC output*1		
8	<revision code=""></revision>		
	<option 1=""></option>	0	
	None		
9	Alarm 1 point		
9	Ramp soak Alarm 1 point + ramp soak	4	
	Alarm 2 points <sup>*2</sup>	F	
	Alarm 2 points + ramp soak*2	Ġ	
	<pre></pre>	<u> </u>	
	None 100 to 240 V AC	N	
10	English 100 to 240 V AC	V	
	None 24 V AC/DC	C	
	English 24 V AC/DC	В	
11	<option 2=""></option>	000	
12	None		
	RS-485 Modbus interface		
	RS-485 Z-ASCII interface Transfer output + Digital input 1 point*3	N00	
13	Transfer output + Digital input 1 point ** Transfer output*3	Q00 R00	
10	Digital input 2 points	T00	
	RS-485 Modbus interface + Digital input 1 point	V00	
	RS-485 Z-ASCII interface + Digital input 1 point	woo	
14	Non-standard parameter setting	F	
	ompatible with two alarms specification (9th code "F" and "G").		

\*1:Incompatible with two alarms specification (9th code "F" and "G").
\*2:Incompatible with two control outputs specification (7th code "A", "C", and "E").
\*3:Incompatible with two control outputs (7th code "A", "C", and "E"), two alarms (9th code "F" and "G"), and 24 V power supply (10th code "B" and "C").

#### Separate order items

DIN rail mounting adapter (for PXR3)	ZZR*CTK368715P1
--------------------------------------	-----------------

	PXR 4 5 6 7 8 9 10 1	1 12 13	
Digit	Specification	Code	
4	<front dimensions=""> 48 × 48mm</front>	4	
5	<input signal=""/> Thermocouple °C Thrmocouple °F RTD P1100 3-wire type I (°C)*1 RTD P1100 3-wire type I (°F)*1 1 to 5V DC 4 to 20mA DC RTD P1100 3-wire type II (°C)*2	T R N S A B W	
6	<control 1="" output=""> Relay contact output Voltage pulse output (24V DC) 4 to 20mA DC output</control>	A C E	
7	<terminal></terminal>	s	
8	Socket type <revision code=""></revision>		
9	<option>     0       None     0       Alarm 1point     1       Ramp soak     4       Alarm 1point + ramp soak     5       Alarm 2points     F       Alarm 2points + ramp soak     G</option>		
10	<instruction manual=""> <power supply="" voltage="">         N           None         100 to 240V AC         N           English         100 to 240V AC         V           None         24V AC/DC         C           English         24V AC/DC         B</power></instruction>		
11 12	<socket> None</socket>		
13	For rail mounting (8-pin) Type: TP48X         100           For panel mounting (8-pin) Type: TP48SB         200           For rail mounting (11-pin) Type: TP411X         400           For panel mounting (11-pin) Type: TP411SBA         500		
Separate order items			
Shunt resistor (250 Ω ±0.1%) ZZPPXR1-A190			
<u> </u>			

#### Scope of delivery

Controller, panel mounting bracket, watertight packing, 250 ohm resistor(for current input), instruction manual

# Micro-Controller X **PXE**





48 × 48 × 63.5 mm

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# Simple and Easy

- 1.6-mm shallow and waterproof front panel
- A user can switch input type among Pt100 RTD and 9 types of thermocouples and their measuring range with front keys
- On-off, PID, and fuzzy control
- Relay contact output or SSR drive output
- Up to two alarm outputs





# Specifications

General	
Power supply voltage	100 V (-15%) to 240 V (+10%) AC, 50/60 Hz
Power consumption	100 V AC: ≤ 5 VA 220 V AC: ≤ 6 VA
Insulation resistance	≥ 20 MΩ (at 500 V DC)
Withstand voltage	Between the power supply and others: 1500 V AC for 1 min *SSR driving output is not isolated from input terminals.
Input impedance	Thermocouple: $\geq$ 1 M $\Omega$
Allowable signal source resistance	Thermocouple: $\leq 100\Omega$
Allowable wire resistance	RTD: ≤10 Ω per wire
Input value correction	Process value shift: ±10% FS Input filter: 0 to 120.0 s settable in 0.1 s steps (first order lag filter)
Noise reduction ratio	Normal mode noise (50/60 Hz): ≥ 40 dB Common mode noise (50/60 Hz): ≥ 120 dB

#### Display and keys

Display and keys		
Туре	LED	
Keys	4 keys	
	PV and SV: 4 digits, 7-segment Status indicator: control output, alarm, standby	

Structure

Installation	Panel flush mounting
Electrical connection	M3 screw terminal
Case	Plastic (non-combustible grade UL94V-0 equivalent) Color: black
IP rating	Front waterproof structure: NEMA4X (IP66 equivalent) (When mounted on panel with our genuine packing. Waterproof feature unavailable in close mounting of multiple units.) Rear case: IP20
Weight	Approx. 100g

**PV** input

F V Input		
No. of inputs	1	
Signal	Thermocouples or RTD *See a separate table for measurement range.	
Sampling rate	0.2 s	
Indication accuracy (at 23°C)	$ \begin{array}{l} (\pm 0.5\% \mbox{ of process value or 1°C whichever is greater) \pm 1digit\pm 1°C \\ \bullet \mbox{Thermocouple -100°C or less: } (\pm 2\% \mbox{ of process value}) \pm 1digit\pm 1°C \\ \bullet \mbox{Accuracy is not assured for ranges from 0 to 500°C for type R thermocouple.} \\ \end{array} $	
Burnout	A user can select either the upper or the lower limit to which the control output should go when a sensor burnout occurs.	

**Control output 1** 

No. of points	1
Туре	Select either of the followings: •Relay contact (SPST-NO): 220 VAC / 30 VDC, 3A (resistive load) Electrical life: 100,000 operations (rated load) Minimum switching current: 100 mA (24 VDC) •SSR drive (Voltage pulse): ON: 10.2–15 V DC OFF: ≤ 0.5 V DC Maximum current: 20 mA
Alarm or control output 2 (option)	

Alarm or control output 2 (option)			
No. of alarms	≤ 2		
Alarm type	Absolute alarm, deviation alarm, zone alarm with upper and lower limits for each Hold function available Alarm latch, excitation/non-excitation selecting function		
Alarm ON-delay	0 to 9999 s, settable in 1 s steps		
Contact	Relay contact: SPST-NO, 220 V AC/30 V DC, 1 A (resistive load) Electrical life: 100,000 operations (rated load) Minimum switching current: 100 mA (5 V DC) Output cycle: 0.2 s		

\*In the heating and cooling dual control, the alarm output 1 functions as the control output 2.

# Ordering Code

# P X E 4 T Y 2 - Y 0 0 0 - E

Digit	Specification	Code
4	<front dimensions=""></front>	
4	48 × 48mm	4
5	<input signal=""/>	
5	Thermocouple, RTD Pt100 [°C]	Т
	<control output=""></control>	
6	Relay contact output	A
	SSR drive output	С
7	-	Y
8	<revision code=""></revision>	2
	<alarm output=""></alarm>	
9	1 point	1
9	2 points	2
	2 points (independent COM)	J
10	<instruction manual=""></instruction>	
10	Japanese/English/Chinese	Y



#### Control

Control type	On-off, PID, fuzzy, two-degree-of-freedom PID
Parameters	
Proportional band (P)	0.1 to 999.9% of measuring range settable in 0.1% steps
Integration time (I)	0 to 3200 s settable in 1 s steps
Differential time (D)	0 to 999.9 s settable in 0.1 s steps
	Proportional action when I, D = 0.
Proportional cycle	1 to 150 s, settable in 1 s steps
Control cycle	0.2 s
Anti-reset windup	0 to 100% of measuring range Automatically validated at auto tuning
l bustana da barad	0 to 50% of measuring range
Hysteresis band	For on-off action only
Other functions	For on-off action only
,	For on-off action only on non-volatile memory
Other functions Data backup at power	
Other functions Data backup at power outage	on non-volatile memory by watchdog timer
Other functions Data backup at power outage Self-diagnosis	on non-volatile memory by watchdog timer
Other functions Data backup at power outage Self-diagnosis Operation and sto	on non-volatile memory by watchdog timer rage conditions

#### Range(°C) Input signal PT1 -200 to 850 RTD -199.9 to 500.0 PT2 0 to 800 0.0 to 400.0 J1 J2 K1 0 to 400 K2 to 1200 -200 K3 0.0 to 400.0 T1 -200 to 400 Thermocouple -199.9 to 400.0 T2 R 0 to 1600 В 0 to 1800 S 0 to 1600 E –200 to 800 Ν 0 to 1300 PL-2 0 to 1300

Scope of delivery

Controller, panel mounting bracket, watertight packing, instruction manual

Separate order item

Terminal cover ZZPPXR1-A230

# Digital Controller PXH



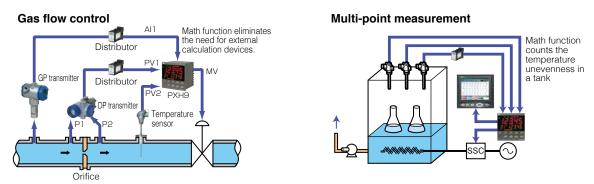
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96 × 96 × 81.5 mm

# High Speed and High Accuracy

- Fast sampling: 50 ms
- Reading accuracy: 0.1%
- 5-digit display can show hundredths place
- Universal input (up to 2 points)
- 9 DI + 9 DO
- 1 AI + 2AO
- Relay contact, SSR/SSC drive, 4-20 mA DC, or motor-operated valve control output
- 64 steps ramp soak function
- Math function
- Pre-installed program templates
- RS-485 communication



MSA SYSTEM - (11) 3961-1171 - comercial@msacontrol.com.br

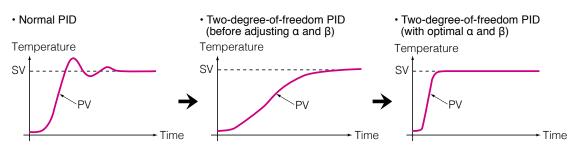


# **Control Functions**



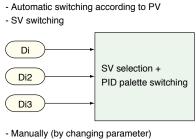
### **Two-Degree-of-Freedom PID**

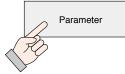
Suppresses overshoot and undershoot occurs at startup or at SV change, or due to disturbances.



## **PID Palette**

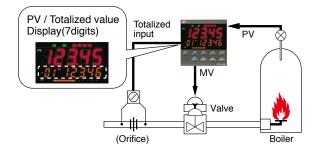
PID palette is pre-installed program templates that allow easy configuration for various applications. You can switch among seven palettes by the following three methods.





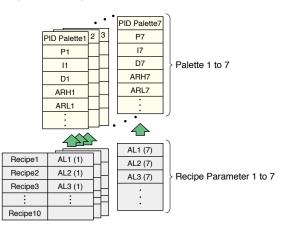
## **Totalizer**

By combining the analog totalizer with the calculation function, you can obtain the flow rate after temperature and pressure compensation.



# **Recipe**

A user can add up to 10 parameters to each PID palette. This allows more optimal batch process control.



# **User Key**

PXH has three user keys to which you can allocate various functions.







#### General

Power supply voltage	100V AC (-15%) to 240 V AC (+10%), 50/60 Hz		
Power consumption	100 V AC: ≤ 15 VA 220 V AC: ≤ 20 VA		
Insulation resistance	≥ 20 MΩ (at 500 V DC)		
Withstand voltage	Between the power source and other terminals: 1500 V AC for 1 min Between the relay output and other terminals: 1500 V AC for 1 min Others: 500 V AC for 1 min		
Input impedance	<ul> <li>Thermocouple, mV input: ≥ 1 MΩ</li> <li>Current input: 250 Ω</li> <li>Voltage input: 1 MΩ</li> </ul>		
Allowable input voltage:	<ul> <li>DC voltage input: ≤ ±35 V</li> <li>Current input: ≤ ±25 mA</li> <li>Thermocouple, RTD, mV input: ≤ ±5 V</li> </ul>		
Effect of signal source resistance	<ul> <li>Thermocouple, mV input: ±0.1%FS per 100 Ω</li> <li>Voltage input: ±0.1%FS per 500 Ω</li> </ul>		
Allowable wire resistance RTD: ≤ 10 Ω per wire			
Input value correction	User adjustment: ±50%FS both for zero point and span point     Square-root extractor: OFF or cut point from 0.0 to 125.0%     First-order lag filter: 0.0 to 900.0 s     Linearizer: Makes a line chart in which 16 data points are     connected by straight lines		
Noise reduction ratio	Normal mode: 40 dB (50/60 Hz)     Common mode: 120 dB (50/60 Hz)		

#### Display and keys

Туре	LED
Keys	9 keys
Cotents	PV: 7-segment, 5-digit SV/MV: 7-segment, 5-digit Parameter number: 7-segment, 2-digit Bar graph: 12-segment Status indicator: standby, control output, alarm, control mode
Structure	
Installation	Panel mounting
Electrical connection	M3 screw terminal
Case	Plastic, gray
IP rating	Equivalent to IP66 and NEMA 4X
Weight	Approx. 500 g
PV input	1
No. of inputs	1 or 2
Signal	Thermocouples, RTD, voltage, or current *See a separate table for measurement range.
Sampling rate	50 ms
Indication accuracy (at 23°C)	Thermocouple: (±0.1%FS ±1digit ±1°C) or ±1.5°C, whichever is larger Thermocouple B, 0–400°C range: ±5%FS ±1digit ±1°C Thermocouple R, 0–500°C range: ±1%FS ±1digit ±1°C     RTD: (±0.1% FS ±1digit) or 0.25°C, whichever is larger Voltage, current: ±0.1%FS ±1digit
Burnout	In the thermocouple input version or the RTD input version, a user can select either the upper or the lower limit to which the control output should go when a sensor burnout occurs.
Digital input	
No. of inputs	4 to 9
Switch	Volt-free contact or transistor
Contact capacity	12 V DC, about 2 mA (per point)
Input pulse width	≥ 200 ms
Functions	Control mode changeover, EX-MV selection, SV changeover, Control standby, Auto-tuning start, Timer start, Alarm latch cancel
Analog input (op	tion)
No. of inputs	1
Signal	DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC     Valve position feedback signal (potentiometer): resistance range:     100Ω to 10KΩ, 3-wire

Control output					
	Control output 1	Control output 2 (for heating and cooling control)			
No. of points	1 select one among four.	1			
Туре	Select one anong tour. Relay contact output: SPDT contact (DO4) SSR/SSC driving output: Rating: 12 V DC (10–15 V DC) 4–20 mA DC Motor-operated valve operation pulse output (open–close output): SPST-NO contact x 2 (with interlock circuit)	select one among three. • Relay contact output: SPST-NO (DO3) • SSR/SSC driving output: Rating: 12 V DC (10–15 V DC) • 4–20 mA DC			
Control					
Control type	Two-degree-of-freedom PID				
Control mode	Auto/manual/remote (changeover is available by key operation, digital input, or communication)				
Control template	allows a user to switch among the operation block and the I/O settings.				
Parameters	(Basic control type and valve control type)	(Heating and cooling control type)			
Proportional band (P)	0.0 to 999.9%, ON/OFF (2-position) operation at P = 0	0.0 to 999.9%			
Integration time (I)	0.0 to 3200.0 s, Integral operation OFF at $I = 0$	0.0 to 3200.0 s, Integral operation OFF at $I = 0$			
Differential time (D)	0.0 to 999.9 s, Derivative operation OFF at $D = 0$	0.0 to 999.9 s, Derivative operation OFF at $D = 0$			
Proportional cycle	1 to 150 s, For SSR/SSC drive or relay output only	1 to 150 s, For SSR/SSC drive or relay output only			
Control cycle	50 ms	50 ms			
Anti-reset windup Hysteresis band	0 to 100% of measurement range 50% of measurement range,	0 to 100% of measurement range 50% of measurement range,			
Number of SV and	for on-off control only 7	for on-off control only 7			
PID patterns					
Alarm					
No. of alarms	≤ 8 PV (H/L limit, absolute/deviation, b	and), PV variation ratio, SV H/L			
Alarm ON-delay	limit, device error 0 to 9999 s, 0 to 9999 min				
Digital output					
No. of outputs	2 (DO3 & DO4) to 9				
Contact	SPST-NO contact (except for DC     SPDT contact (DO4)     Contact capacity: 220 V AC / 30 V     Contact life: 100,000 operations (r	DC, 1A (resistive load)			
Functions	Alarm, timer, control output (DO4)				
Transfer output					
No. of points	≤ 2				
Туре	4–20 mA				
Contents	PV, SV, MV, DV, AIM, MVRB, TV				
Power supply out	tput for transmitter				
Rating	24 V DC (17–30 V DC)				
RS-485 communi	cation				
Modbus RTU,	bit serial, asynchronous communic	ation			
Serial characteristics	Data bits: 8 bits. Parity: odd, even Baud rate: 9600 bps, 19200 bps, 3	, none			
Connection	≤ 32 units				
Communication distance	< 500 m (total connection length)				
Other functions					
Ramp soak	64 step ramp soak with guarantee	d soak			
Data backup at power outage	on non-volatile memory				
Self-diagnosis	by watchdog timer				
Math function	Temperature and pressure compe input switching, etc.	nsation, average, H/L selector,			
Operation and st	prage conditions				
Operating temperature	-10°C to +50°C				
Storage temperature	-20°C to +60°C				
lumidity ≤ 90% RH (no condensation)					

# **Ordering Code**

#### P X H 9 A 1 - V 0 **Basic Type**

Digit	Specification	Code
4	<front dimensions=""> 96 x 96 mm</front>	9
5	<number control="" function="" loops="" of=""> 1-loop basic controller</number>	А
6	<pv input=""> 1 point 2 points*1</pv>	1 2
7	<analog input=""> None DC voltage: 1 point</analog>	0
8	<revision code=""></revision>	1
9	COutput>*3     OUT1     OUT2     Current     Current     Current     Current     Current     Current     SSR/SSC driver     SSR/SSC driver     Current	1 2 5 A B
10	<power supply=""> 100 to 240 V AC</power>	V
11	<communication interface=""> None RS-485</communication>	0 R
12	Cligital input and output>*1.2     DI     DO     4     4     4     9     9     9     9     9     1	0 A B
13	<additional specifications=""> None</additional>	0

\*1:The 6th code "2" (2 inputs) and the 12th code "B" (9 DI and 9 DO) are not compatible. \*2:When you use a relay for the control output 1, the terminal DO4 is allocated to it. \*3:See the matrix on the right side for the function of each output.

	Terminal	DO4	OUT1		OL	T2
	Output Kind	Relay	Current (4 to 20 mA)	SSR/SSC driver	Current (4 to 20 mA)	Transmitter
Code	Function*	Control output or Digital output	Control output or Transfer output	Control output	Transfer output	power supply
9th	1	1	1			
digit	2	1	1		1	
	5	1	1			1
	A	1		1		
	В	1		<b>√</b>	1	

\* If there are two functions listed, a user can select the function by parameter setting

#### 10 11 12 13 P X H 9 F 8 V Heating/Cooling Control Type 0 Digit Specification Code 4 < Front dimensions> 96 x 96 mm <Number of control loops/Function> 9 5 <Number of control loops/Function 1-loop heating/cooling controller <PV inputs 1 point 2 points\*1 <Analog inputs None DC voltage: 1 point <Revision codes <Outputs\*3 OUT1 F 6 12 7 0 8 9 OUT1 Current Current OUT2 None Current SSR/SSC drive Transmitter supply None 1235ABC Current Current SSR/SSC driver SSR/SSC driver SSR/SSC driver Current SSR/SSC drive 10 <Power supply> 100 to 240 V AC V 11 <Communication interface> None 0 Ř RS-485 <Digital input and output>\*1 12 DI DO 0 A 2 ĥ à <Additional specifications> 13 0 None

\*1:The 6th code "2" (2 inputs) and the 12th code "B" (9 DI and 9 DO) are not compatible. \*2:When you use one relay for the control output, the terminal DO4 is allocated to it. When you use two relays for the control output 1 and the control output 2, the terminal DO3 and DO4 are allocated respectively.

\*3:See the matrix on the right side for the function of each output.

#### Scope of delivery

Controller, mounting bracket, watertight packing, unit label, terminating resistor (for version with RS-485 communication only), instruction manual

#### 5 7 8 9 10 11 12 13 1 V 0</td РХН9 Motorized Valve Control Type Digit Code Specification Front dimensions> 96 x 96 mm Number of control loops/Function> 1-loop motorized valve controller (with valve position feedback input) 1-loop motorized valve controller (without valve position feedback input) Specification 4 9 5 D S 6 PV input> 1 point 2 points\*1 1 2 <Analog input> None DC voltage: 1 point 7 0 8 <Revision code> <Output>\*2 OUT2 None Cur 9 OUT1 Current Current 12 Current Transmitter supply 10 V 11 0 R 12 DO 0 4 В 9 <Additional specifications> 9 13 0 None

NTRC

\*1:The 6th code "2" (2 inputs) and the 12th code "B" (9 DI and 9 DO) are not compatible. Select "2 points" when a remote SV input (RSV) is required. \*2:"D" for the 5th digit and "1" for the 7th digit cannot be specified at the same time. \*3:DO4 is used as control output. If 2 or 3 DO points are required for event output, specify the code A, and if 4 to 8 DO points are required, specify the code B.

[	Terminal	DO4	OUT1	OL	IT2
	Output Kind	Relay	Current (4 to 20 mA)	Current (4 to 20 mA)	Transmitter
Code	Function*	Valve control output	Transfer output	Transfer output	power supply
9th	1	· ·	✓		
digit	2	1	1	1	
	5	✓	✓		1

If there are two functions listed, a user can select the function by parameter setting.

		r						
	Terminal	DO3	DO4	OU	T1	00	T2	
	Output Kind	Relay	Relay	Current (4 to 20 mA)	SSR/SSC driver	Current (4 to 20 mA)	SSR/SSC driver	Transmit-
Cod	Function*	Control output or Digital output	Control output or Digital output	Control output or Transfer output	Control output	Control output or Transfer output	Control output	ter power supply
9th	1	<ul> <li>✓</li> </ul>	1	✓				
digi	2	<ul> <li>✓</li> </ul>	<ul> <li>✓</li> </ul>	1		1		
l'uidi	3	✓	<ul><li>✓</li></ul>	1			~	
	5	<ul> <li>✓</li> </ul>	1	✓				×
	A	<ul> <li>✓</li> </ul>	<ul> <li>✓</li> </ul>		✓			
	B	✓	<ul> <li>✓</li> </ul>		~	<		
	C	<ul> <li>✓</li> </ul>	1		✓		✓	

\* If there are two functions listed, a user can select the function by parameter setting.

#### Range [°C] Input signal Min Resolution (°C) Max. 150 to 850 0 to 1000 RTD Pt100 0.01 0 to 15 Thermocouple 0 to 400 0 to 1200 0 to 1600 0 to 400 0 to 160 K 0. 0 to 1800 0 to 1800 0 to 180 0 to 160 В 0.1 200 to 400 0 to 800 0 to 1800 0 to 1300 -200 to 800 0 to 1800 0 to 1300 0. PR40/20 0.1 N PL-II WRe5-26 1 to 5 V 0 to 5 V 0 to 10 V 0 to 10 V 0 to 1300 0 to 1300 0.1 0 to 2300 0 to 2300 DC voltage -19999 to 99999 1/10000 (Range where scaling digit is allowed) 4 to 20 mA 0 to 20 mA DC current Motorized valve position feedback Potentiometer 100 to 10 k 1/1000 digit

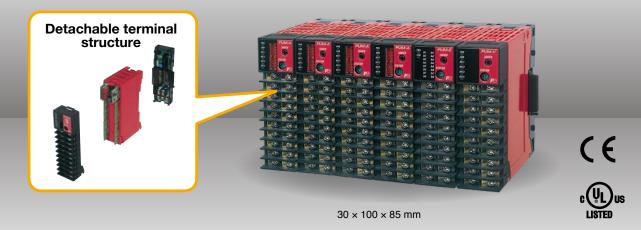
#### Separate order items

Measurement range

Terminal cover	ZZP PXR1-B230	Two pieces are necessary per unit.	
PC loader interface cable	ZZP PXH1*TK4H4563	For RS-232C Interface	

# Multi-Loop Module Type **Temperature Controller** PUM





- Control Module
- Event Input/Output
- Analog Input/Output
- Analog Input
- Analog Output
  - CC-LINK
- Programless Communication with Mitsubishi PLC
- PROFIBUS
- Ethernet

# Smart!

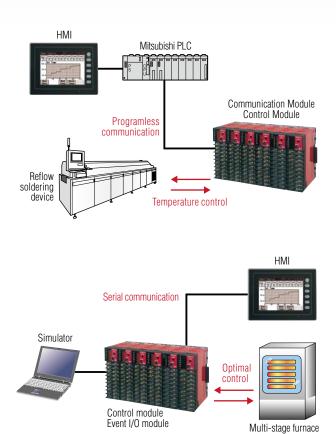
- Up to 64 loops (4 loops  $\times$  16 units)
- Heater break alarm by using CT, up to 8 points
- Communication with PLC

# Easy!

- Detachable terminal
- · Easy-to-use software
- · Easy mounting onto DIN rail

# Fast!

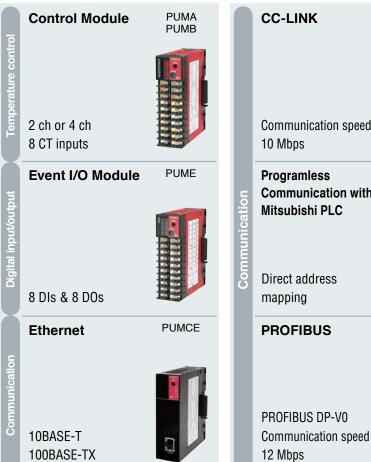
- High-speed data transmission (RS-485 / 115.2 kbps or 230.4 kbps)
- Sampling time: 200 ms



20

MSA SYSTEM - (11) 3961-1171 - comercial@msacontrol.com.br

# Variations







**Analog Input** Module /out

input

00

е С

4 Als

4 AOs

Transfer output

PUMN



**Analog Output** Module

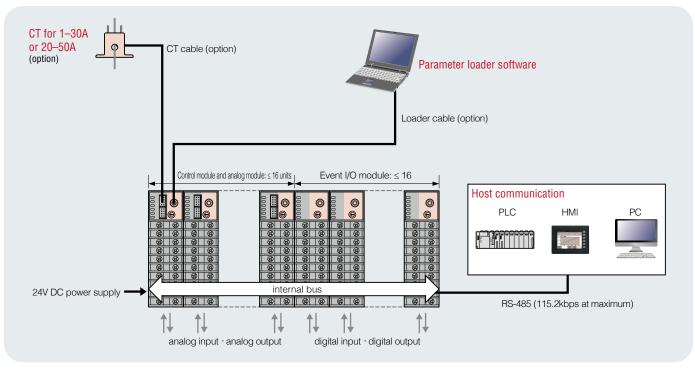
Remote input

PUMT



# System Configulation Example

- · Control module (PUMA, PUMB) + analog I/O module (PUMV, PUMN, PUMT): up to 16 units in total
- · Event I/O module (PUME): up to 16 units



# Digital Thermostat **PXR3**





#### 48 × 24 × 98 mm

# Temperature Alarm with On-Off Contact Output Ideal for Overheat Detection

- Thermocouple input or thermistor input
- Waterproof front panel: IP66 and NEMA 4X equivalent
- Up to two alarm outputs (H, L, HH, LL alarm available)
- Alarm setting in 1°C steps
- Panel mounting
- DIN rail mounting or wall mounting with optional adapter
- Lightweight 150 g
- Simple operation with three front keys
- European-style terminal

# **Specifications**

Power supply voltage	100 (-15%) V to 240 (+10%) V AC, 50/60 Hz Power consumption: $\le$ 6 VA (at 100 V AC), $\le$ 8 VA (at 240 V AC),
Input	Number of inputs: 1 Input signal and measurable range: see Table 1. Allowable signal source resistance: thermocouple input $\leq 100\Omega$ Measurement cycle: $\leq 2$ seconds Burnout function (open-circuit detection): you can set the output upon an open-circuit to the upper limit or the lower limit Input impedance: thermocouple input $\geq 1$ M $\Omega$ Input filter: first-order lag filter, configurable in 0.5-second steps, within 0–90 seconds Input compensation: configurable within ±10% of measurement
Display and keys	range Green LED 7-segment 4-digit alphanumeric display Display contents: measured value, alarm 1 setpoint, alarm 2 setpoint, parameter name, parameter value 3 keys, with key lock function
Accuracy	Indication accuracy: See Table 1 (Error of temperature sensor is not included) Reference junction compensation accuracy: ±1°C (at 23°C)
Alarm output	SPST-NO contact, 1 or 2 points Contact capacity: 220 V AC / 30 V DC, 1A (resistive load) Mechanical life of contact: 10 milion times (no load) Electrical life of contact: 100 thousand times (rated load) Output cycle: 0.5 seconds Alarm type: (high or low absolute alarm, hold function available) Alarm setpoint: configurable in 1°C steps, within 0–100% of mea- surement range Hysteresis: configurable in 1°C steps, within 0–110% of measure- ment range Alarm delay: configurable within 0–120 seconds
Operating conditions	Ambient temperature: -10°C to +50°C Ambient humidity: ≤ 90% RH (no condensation)
Installation	Panel mount, or DIN rail or wall mount when using DIN rail mounting adapter (separate order item)
Electrical connection	European-style terminal
Case	Plastic (equivalent to non-combustibility grade UL94V-0), black
IP rating of front panel	IP66 (equivalent to NEMA 4X)
Weight	Approx. 150 g
<b>.</b>	

#### Measurement range

Sensor		Range (°C)	Indication accuracy
Thermocouple	J	0 to 800	±0.5% FS ±1digit ±1°C
	К	0 to 1200	±0.5% FS ±1digit ±1°C
	R	0 to 1600	±0.5% FS ±1digit ±1°C
	Т	0 to 400	±0.5% FS ±1digit ±1°C
	E	0 to 600	±0.5% FS ±1digit ±1°C
Thermistor	PB-36	0 to 100	±4°C

Notes:

 The thermostat cannot deliver the accurate indication when the sensor is the type R thermocouple and the temperature is in the range between 0 and 500°C. • You cannot switch the input type between the thermistor and the thermocouple. You can

If you change the input type among the five type of thermocouples by using the front keys.
If you change the input type, be sure to change the measurement range setting accordingly.
The indication accuracy of thermocouple does not include the reference junction compensation error (±1°C).

The indication accuracy of thermistor does not include the error of sensor.



#### Ordering code

Sensor		Number of alarms	Model code
Thermocouple	Not provided	1	PXR3TAY2-0V061
		2	PXR3TAY2-1V061
Thermistor	Provided	1	PXR3HAY2-0V061
		2	PXR3HAY2-1V061

#### Scope of delivery

Thermostat, panel-mounting adapter, front waterproof packing, instruction manual	
*For the thermistor input version, a thermistor sensor is additionally provided.	

#### Separate order item

DIN rail adapter	ZZP*CTK368715P1

#### **Default setting**

Measurement range	Type K thermocouple: 0°C to 1200°C Thermistor: 0°C to 100°C
Alarm setpoint         Type K thermocouple, 1 alarm: upper limit 1200°C           Type K thermocouple, 2 alarms: lower limit 0°C, upper limit 120           Thermistor, 1 alarm: upper limit 100°C           Thermistor, 2 alarms: lower limit 0°C, upper limit 100°C	
Alarm hysteresis width	1°C
Alarm delay time	0 seconds
Indication	Measured value
Burnout	Upper limit
Input filter	5 seconds
Input value compensation	0%

#### Attached thermistor sensor

Measurement range	0°C to 100°C
Constant B	3990 K
Nominal resistance	6 kΩ (°C)
Lead wire	Heat-resistant vinyl chloride, black, 520 mm, Temperature range: -20°C to +105°C
Accuracy	≤ 2°C

#### **Dimensions (unit: mm)**

MAX.	Epoxy resin (black)	Heat-resistant parallel vinyl chloride wire (12/0.18 TA)(black)	
ø6.5	20 MAX.	About 520	-5

#### Thermistor sensor for replacement

ZZP\*CTK7L3941P1



# MSA CONTROL Indústria Elétrica Ltda. MSA SYSTEM Elétrica Ltda.

Rua Iapó 334 - Casa Verde - São Paulo - SP - CEP:02512.02

Tel/Fax: (11) 3961.1171 - comercial@msacontrol.com.br

ww.msasystemelectric.com.br & www.msacontrol.com.br

Please read the following instructions carefully before operating the Digital Temperature Controller

# **AWARNING** Over-Temperature Protection

Any control system design should take into account that any part of the system has the potential to fail.

For temperature control systems, continued heating should be considered the most dangerous condition, and the machine should be designed to automatically stop heating if unregulated due to the failure of the control unit or for any other reason.

The following are the most likely causes of unwanted continued heating:

- 1) Controller failure with heating output constantly on
- 2) Disengagement of the temperature sensor from the system
- 3) A short circuit in the thermocouple wiring
- 4) A valve or switch contact point outside the system is locked to keep the heat switched on.

In any application where physical injury or destruction of equipment might occur, we recommend the installation of independent safety equipment, with a separate temperature sensor, to disable the heating circuit in case of overheating.

The controller alarm signal is not designed to function as a protective measure in case of controller failure.

Fe Fuji Electric Co., Ltd.